

# **I would like to touch on Three Subjects Today**

**1**

**Why is Normal Alignment Normal?**

**Where is the Deformity in Limb Malalignment?**

**How Much is the Deformity?**

**2**

**Discuss Osteotomy for Limb Malalignment**

**3**

**The Mystery of Anterior Knee Pain**

# **Limb Alignment**

## **Limb Mal-alignment**

**How to Locate the Deformity  
in Mal-alignment**

# How to Design a Limb

Look to Pauwels the father of modern orthopaedic biomechanics who tells us the limbs are designed the way they are to transfer the weight of the body through the center of the Knee Joint to the ground and to allow motion

## INVITED ARTICLE

### IATROPHYSICS TO BIOMECHANICS

FROM BORELLI (1608-1679) TO PAUWELS (1883-1980)

PAUL MAQUET

From Liège

In his *Traité de l'homme et de la formation du fœtus*, published in 1675, René Descartes considered the human body as a material machine directed by a rational soul (which he located in the pineal gland). His work was, perhaps, the first attempt to contain all animal physiology in a mechanistic theory. The famous *De motu animalium* of Giovanni Alfonso Borelli is, however, the very first comprehensive treatise on biomechanics, although at that time it was called iatrophysics, meaning physics applied to medicine. Borelli held the chair of mathematics at the University of Pisa where he worked closely with Malpighi who was professor of theoretical medicine. Their collaboration is an excellent example of the effectiveness of co-operation by scientists from different disciplines. Malpighi is quoted as saying: "What progress I have made in philosophising stems from Borelli. On the other hand, dissecting living animals at his home and observing their parts, I worked hard to satisfy his very keen curiosity". Borelli had published two earlier books *De vi percussione* in 1667 and *De motionibus naturalibus a gravitate pendentibus* in 1670, both paving the way for the *De motu animalium*, the first part of which was published in Rome in 1680, just after his death, and the second in 1681.

In the first part Borelli analysed the function of the locomotor apparatus in man, quadrupeds, birds, fishes, worms, flies, etc., all from a mechanical standpoint. He calculated the forces developed by the muscles and those transmitted across the joints during activities such as carrying a load, walking, running, jumping, skating, swimming, and flying. He recognised that the muscles, acting with generally short lever arms, balance the body-weight which usually acts with a much longer lever arm so that the joints must transmit forces at least equal to

and usually several times greater than the weight of the body or that part of it which they sustain (Fig. 1). The so-called balance of Pauwels (1935) (Fig. 2) had in fact been clearly described before 1680.

Borelli was probably also the first to determine experimentally the centre of gravity of man, by having

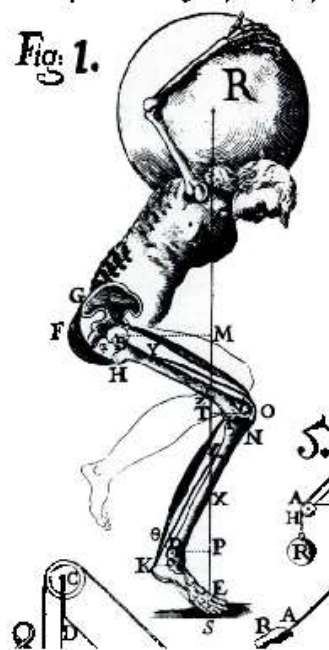


Fig. 1

From Borelli: how muscles balance the body and a load carried on the neck.

P. Maquet, MD, Consultant Orthopaedic Surgeon, Clinique Ste Elisabeth, Liège  
Thier Bussel, 25, B-1920 Aywaille, Belgium

© 1992 British Editorial Society of Bone and Joint Surgery  
0301-620X/92/3379 \$2.00  
*J Bone Joint Surg [Br]* 1992; 74-B:333-9.

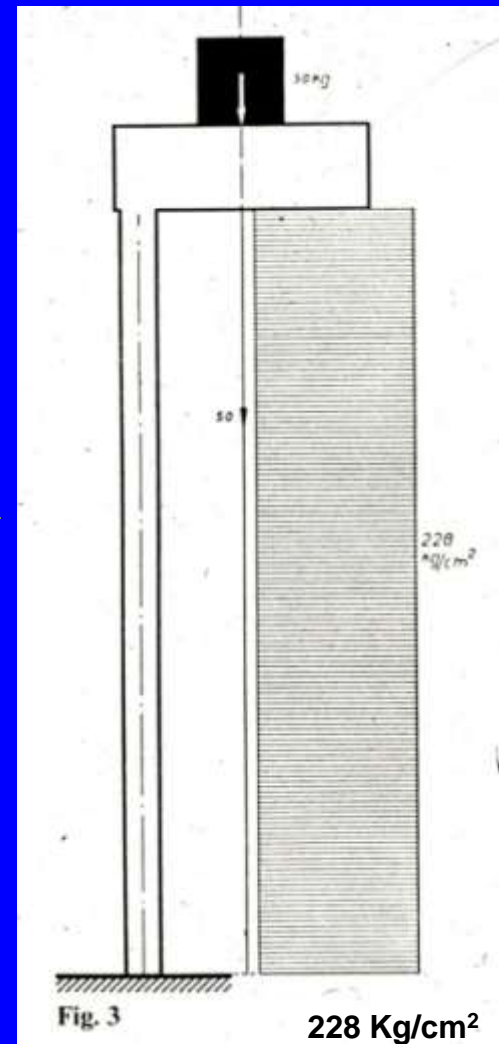
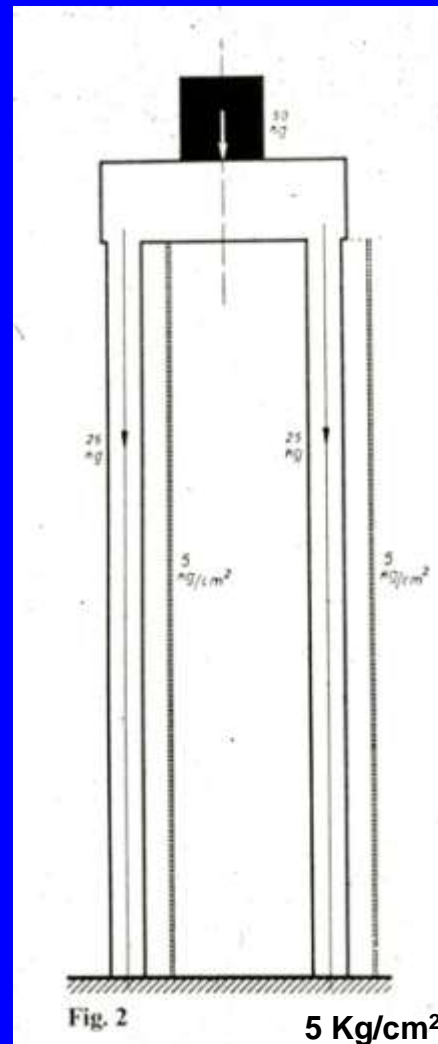
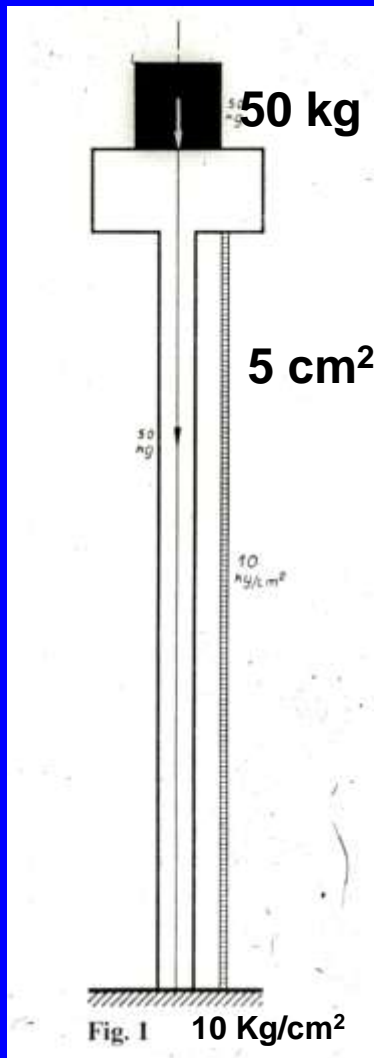
**Pauwels asked the question:**

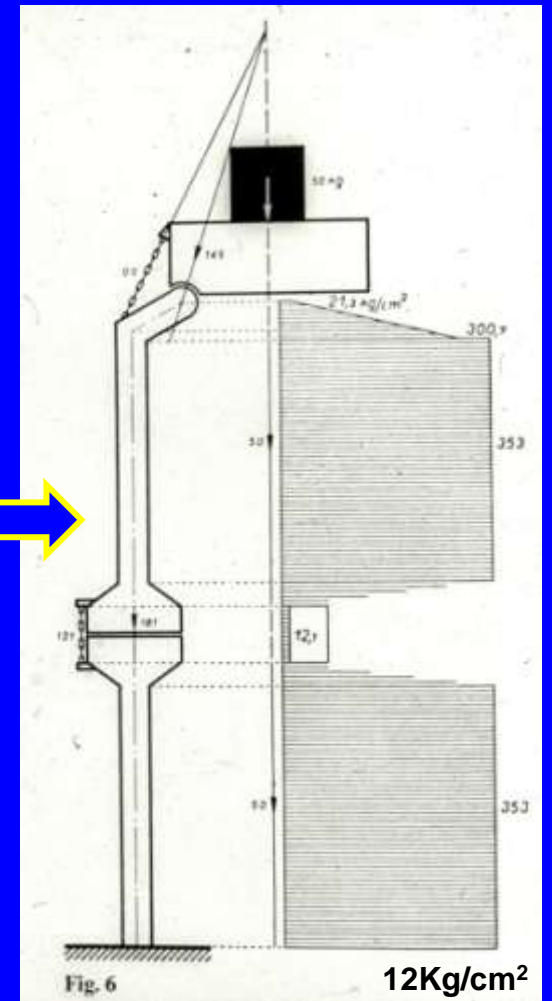
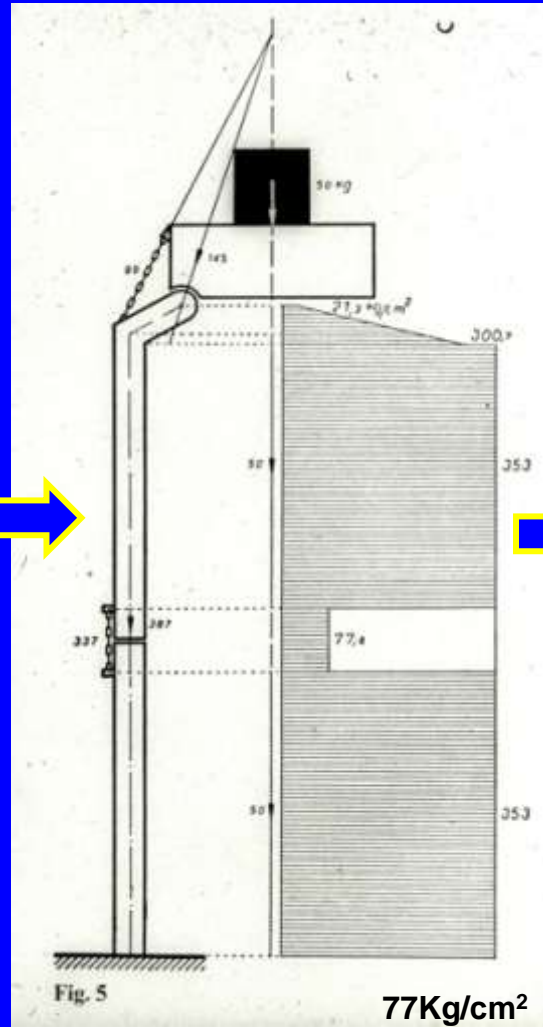
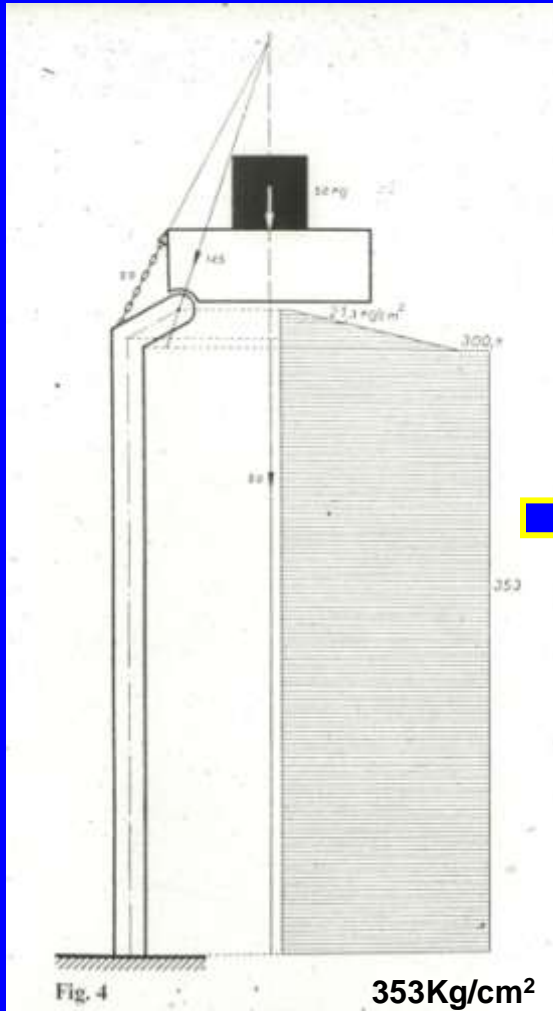
***Why are legs shaped the way they are?***

# *Why are legs shaped the way they are?*

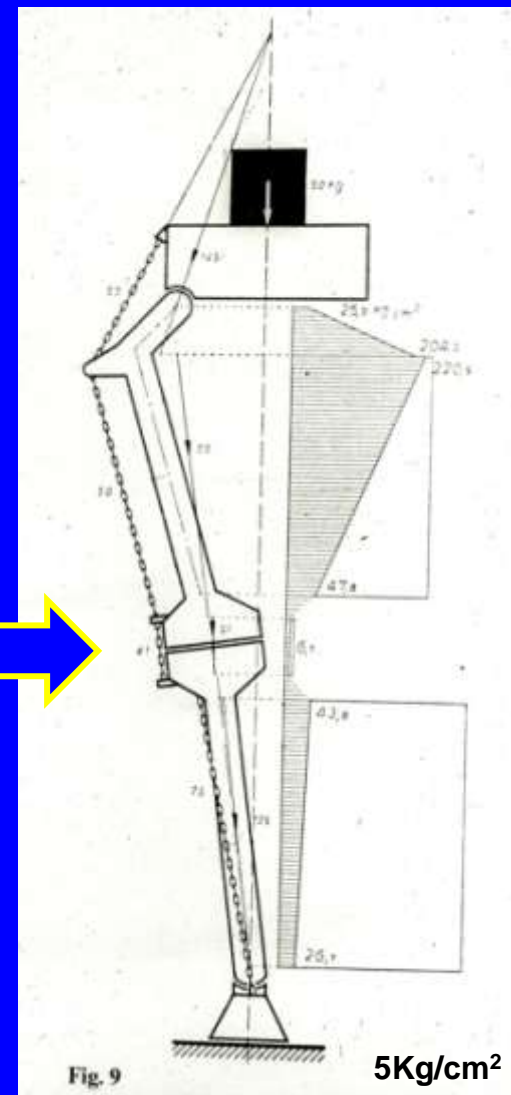
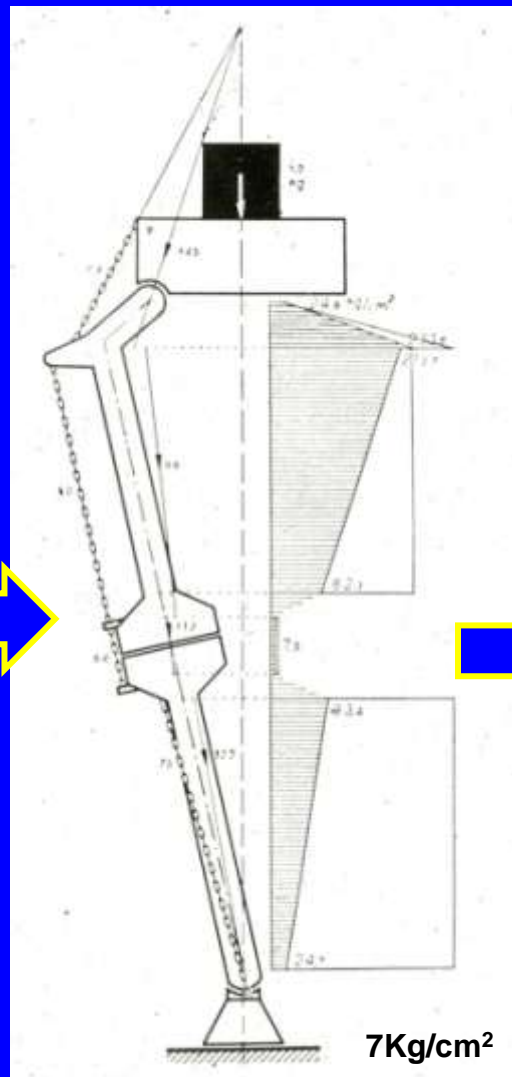
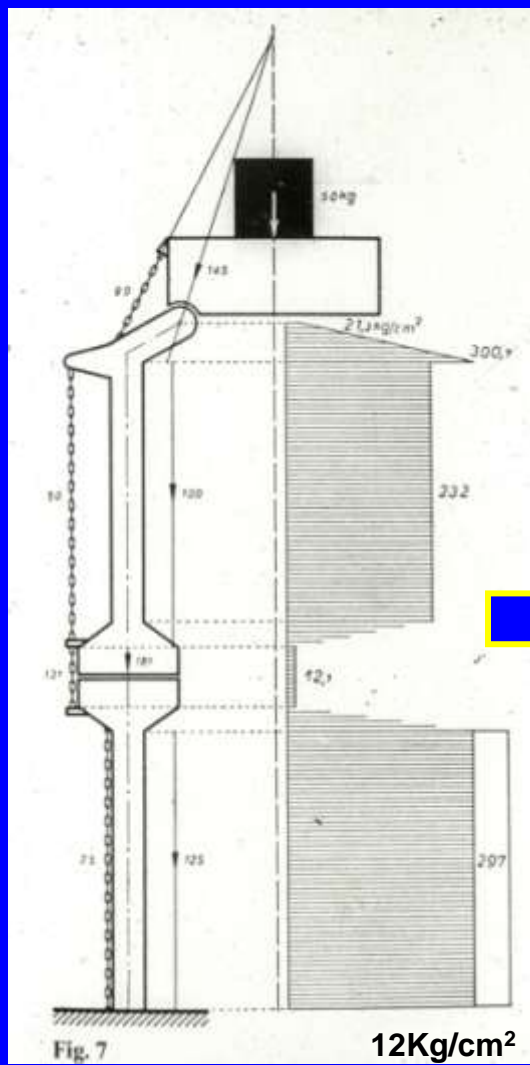


**Pauwels showed how the limb was designed to allow weight transfer within biological tolerance levels.**









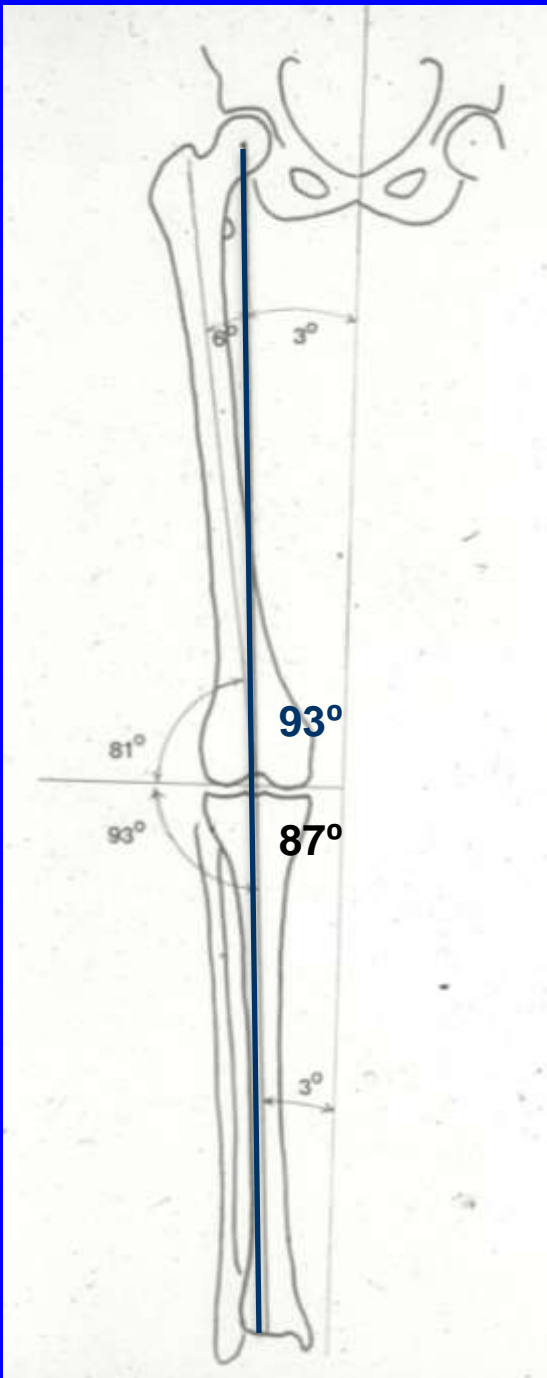


**Legs are shaped to**

**To move the knee joint  
beneath the center of  
gravity,**

**to increase the contact area  
which transmits the body  
weight to the ground**

**And to allow a horizontal  
joint surface.**



**Which Brings us back to the  
Point of this First Talk**

**What is normal Alignment?  
and  
Where is a Limb Mal-alignment  
Deformity Located?**

**The Mechanical Axis is  
a line drawn from  
the center of the femoral head  
to  
the center of the talus**

**It normally passes through the  
knee joint a few mm medial to  
the center of the knee joint**



**This is  
Slight  
Varus**

**The Normal Limb has the knee joint  
moved toward the center line of the body**

**by inclining the mechanical axis inward  
from the vertical**

**by a valgus tibial femoral angle**

**with a horizontal joint line.**

# Normal Alignment

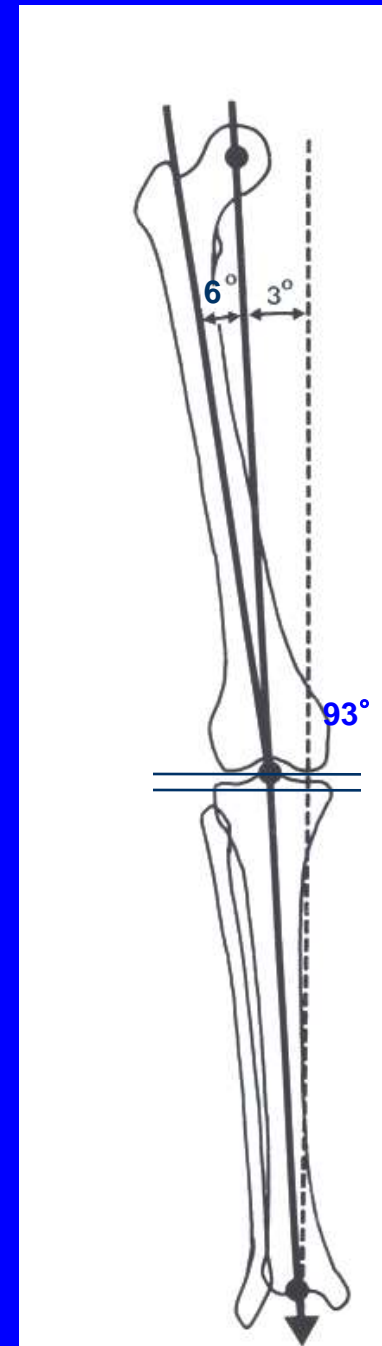
Mechanical Axis goes through the center of the knee

Mechanical Axis =  $3^{\circ}$   
from Vertical

Joint Line is Horizontal

Therefore the Angle Between  
Femoral Head & Distal Femur =  
 $93^{\circ}$  on Medial Side

Proximal Tibia to Ankle  
=  $87^{\circ}$  on Medial Side



MA

Lat.

Med.

$87^{\circ}$   $93^{\circ}$

$93^{\circ}$   $87^{\circ}$

**To Understand  
Alignment Deformity**

**Ask 4 Questions**

## Answer 4 Questions!

1. Where is the Mechanical Axis?
2. Is the Deformity Varus or Valgus?
3. What is the Total Deformity?
4. Is the Deformity located in the Femur?  
Tibia?  
Joint?





**Locate  
Center of Head of Femur**

# **1. Where is the Mechanical Axis?**



**Locate the  
Center of  
the talus**

**Connect Center of Femoral Head  
to Center of Talus**

**This is *Mechanical Axis***

**2. Is it Varus or valgus?**

***If* Varus it is Medial to Knee**

***If* Valgus it is Lateral to Knee**



**Varus**

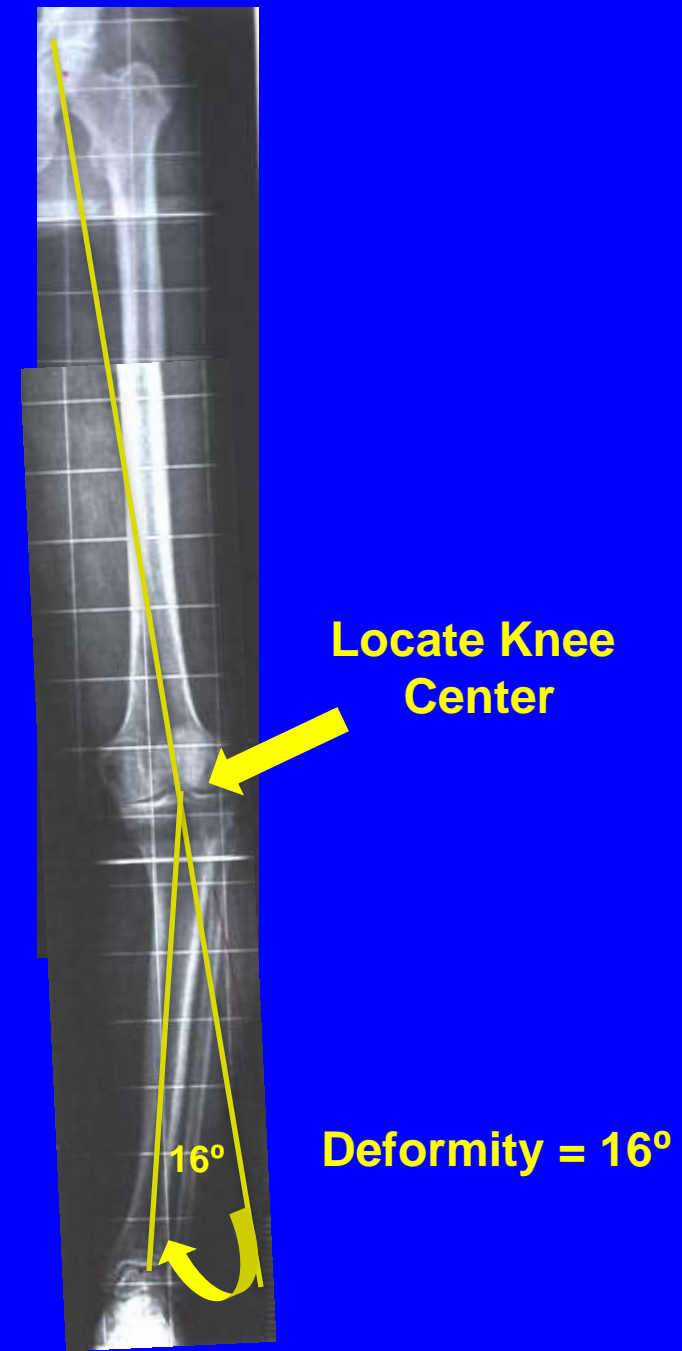
**The Mechanical  
Axis is Medial to  
The Knee Joint  
center**

### 3. What is the Total deformity?

**Draw a Line from  
Hip Center through the  
Knee Center**

**Draw a 2<sup>nd</sup> Line from  
Knee to Ankle Center**

**The Angle between  
these lines is the  
Total Deformity**



Is there a Deformity in the Joint?

**Draw Line Tangent to Distal Femur**

**Draw line Tangent to Proximal Tibia**

**This is Angle of Deformity at the Joint**

**Joint Deformity**

**May be Ligament Laxity**

**May be Cartilage Loss**

**May be Both**



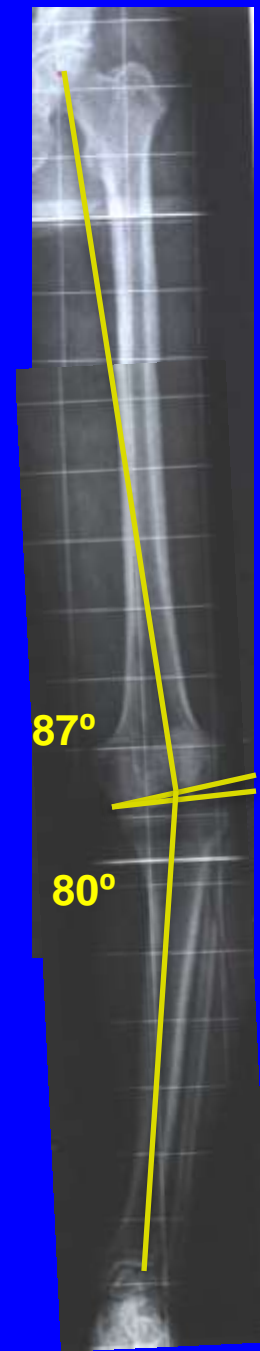
### Question 4:

Is the Deformity in Femur or in Tibia or in the Joint?

Draw line from Hip Center to Distal Femur Center on the Tangent Line  
Should be  $93^\circ$  (on Medial Side)

### Step 7

Draw Line from Ankle Center to Knee Center on the tibial tangent line  
Should be  $87^\circ$  (on Medial Side)



Normal:  
Medial Femur =  $93^\circ$   
Medial Tibia =  $87^\circ$   
Joint =  $0^\circ$

This Case:  
Femur:  $93^\circ - 87^\circ = 6^\circ$   
Tibia:  $87^\circ - 80^\circ = 7^\circ$   
Joint: =  $3^\circ$

Total =  $16^\circ$   
Deformity

Normal Limb:

Medial Femur =  $93^{\circ}$

Medial Tibia =  $87^{\circ}$

Joint =  $0^{\circ}$

This Case - the Deformity:

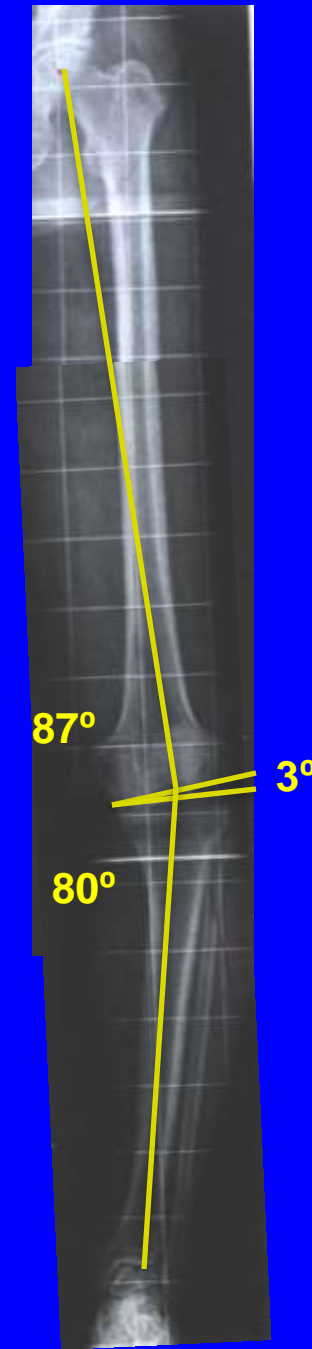
Femur:  $93^{\circ} - 87^{\circ} = 6^{\circ}$

Tibia:  $87^{\circ} - 80^{\circ} = 7^{\circ}$

Joint: =  $3^{\circ}$

Total =  $16^{\circ}$

Femur  $6^{\circ}$  + Tibia  $7^{\circ}$  + Joint  $3^{\circ}$



# Summary of Deformity Analysis

## Answer 4 Questions

1. Where is the Mechanical Axis?
2. Is it Varus or Valgus?
3. How Great is the Deformity?
4. Is the Deformity in the Femur?  
in the Tibia?  
in the Joint?

**The Total Deformity = Femur + Tibia + Joint**  
*Measure and Locate the Deformity in 6 more cases*



## Case 2

Where is the Mechanical  
Axis?



**Where is the  
Mechanical axis?**

**Lateral**

**Obviously a Valgus Deformity**



# How Much is The Deformity?

**19°**

**Where is this 19° Deformity?**

**Measure Femoral Deformity**

**Measure Joint Deformity**

**Measure Tibial Deformity**



## Case 2

Deformity  $19^\circ$

Femur (medial) =  $119^\circ$

$$119^\circ - 93^\circ = 26^\circ \text{ (valgus)}$$

Joint =  $2^\circ$  (valgus)

Tibia (medial) =  $78^\circ$

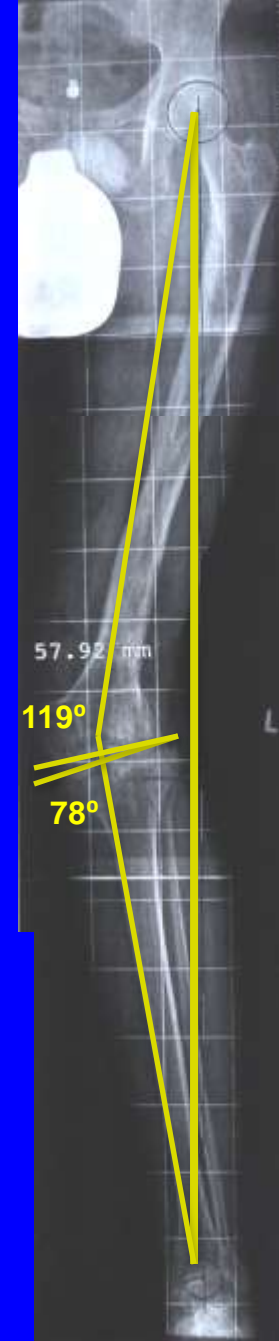
$$87^\circ - 78^\circ = 9^\circ \text{ (varus)}$$

Total:  $26^\circ + 2^\circ - 9^\circ = 19^\circ$

The Femur is in  $26^\circ$  of Valgus

The Joint has  $2^\circ$  of Valgus

The Tibia is in  $9^\circ$  of Varus



## Case 3

What is the Deformity?



## Case 3

### Valgus Deformity

How Much is the Deformity?



# Case 3

**Deformity =  $16^{\circ}$   
Valgus**

**(It is written that a valgus deformity  
should be corrected by a Distal femoral  
osteotomy. Is the deformity in the femur?  
)**

**Where is the Deformity?**





# Case 3

**Valgus Deformity 16°**

**Femur (medially) = 94°**

**94° - 93° = 1° (valgus)**

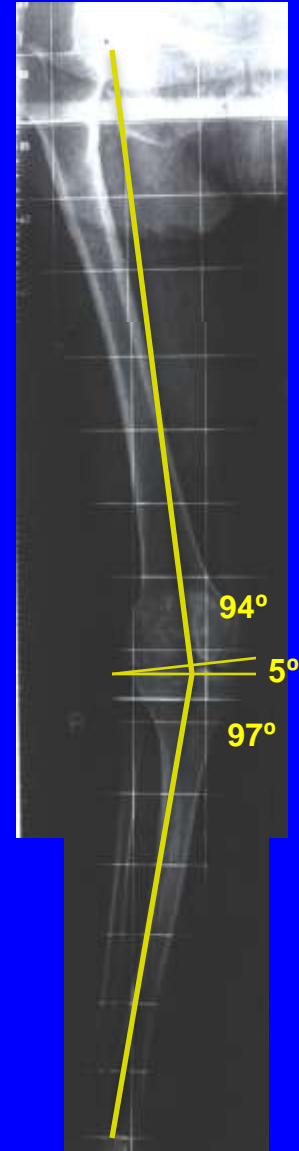
**Joint = 5° (valgus)**

**Tibia(medially) = 97°**

**97° - 87° = 10° (valgus)**

**Total 1° + 5° + 10° = 16°**

**Deformity is 1° Femur, 5° Joint, 10° Tibia**



## Case 4

What is the Deformity?



## Case 4

### Varus Deformity

How Much Deformity?



## Case 4

Deformity =  $13^{\circ}$

Where is the Deformity?  
(Is HTO Indicated?)



# Case 4

## Varus Deformity 13°

Femur = 88°

$93^\circ - 88^\circ = 5^\circ$  (varus)

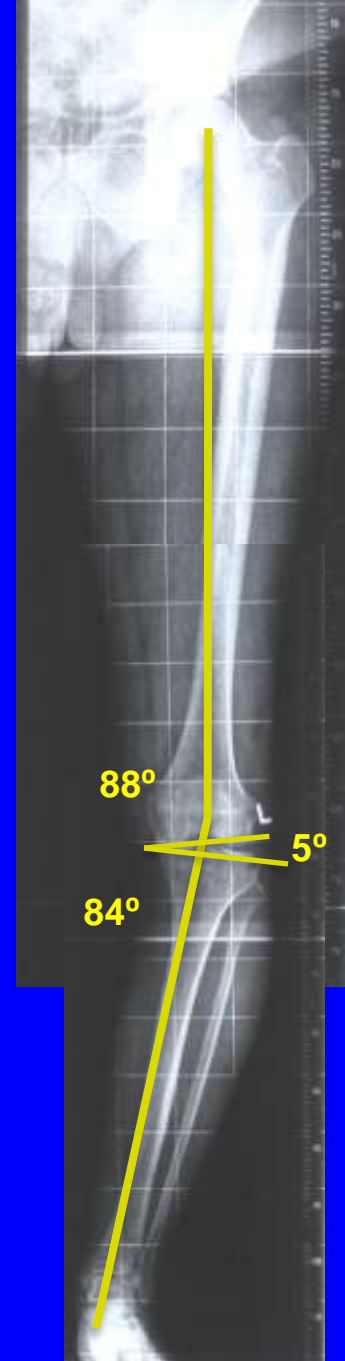
Joint = 5° (varus)

Tibia = 84°

$87^\circ - 84^\circ = 3^\circ$  (varus)

Total  $5^\circ + 5^\circ + 3^\circ = 13^\circ$

Femur = 5° + Joint = 5° + Tibia = 3°



## Case 5

What is the Deformity?



## Case 5

# Valgus Deformity

How much is the deformity?





# Case 5

Deformity =  $32^\circ$

Where is the Deformity?



# Case 5

Deformity =  $32^\circ$  valgus

Femur (medially) =  $87^\circ$

$93^\circ - 87^\circ = 6^\circ$  (varus)

Joint =  $4^\circ$  (valgus)

Tibia (medially) =  $121^\circ$

$121^\circ - 87^\circ = 34^\circ$  (valgus)

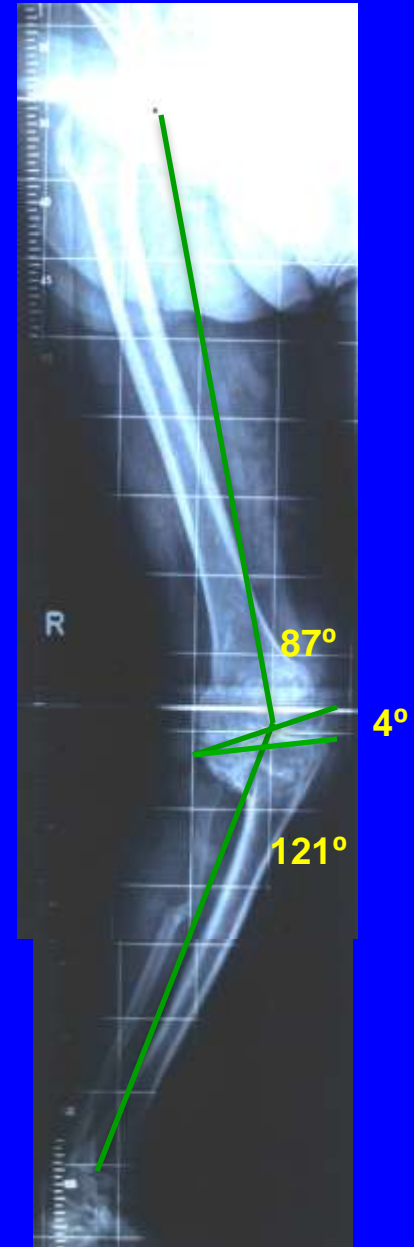
Total  $-6^\circ + 4^\circ + 34^\circ = 32^\circ$

Tibia =  $+34^\circ$ , Femur =  $-6^\circ$ , Joint =  $+4^\circ$

Tibia is Valgus

but

Femur is Varus



# Case 6

**Varus or Valgus?**

**How much?**

**Where?**

**Femur?**

**Joint?**

**Tibia?**



## Case 6

# Mechanical Axis Varus

How Much Varus?



## Case 6

15° Varus

Where is the Deformity?

Femur?

Joint?

Tibia?



## Case 6

Deformity  $15^{\circ}$

Femur (medially) =  $93^{\circ}$   
no deformity

Joint =  $6^{\circ}$  (varus)

Tibia (medially) =  $78^{\circ}$   
 $87^{\circ} - 78^{\circ} = 9^{\circ}$  (varus)

Total  $0^{\circ} + 6^{\circ} + 9^{\circ} = 15^{\circ}$

Femur  $0^{\circ} +$  Joint  $6^{\circ} +$  Tibia  $9^{\circ}$





Unstable –Can't Walk  
Patella stays Dislocated





# Dislocating Patella after Revision TKA



# Recurrent Dislocation Patella

What is Alignment?

Valgus

How Much?



# Recurrent Dislocation Patella

15° Valgus  
Deformity



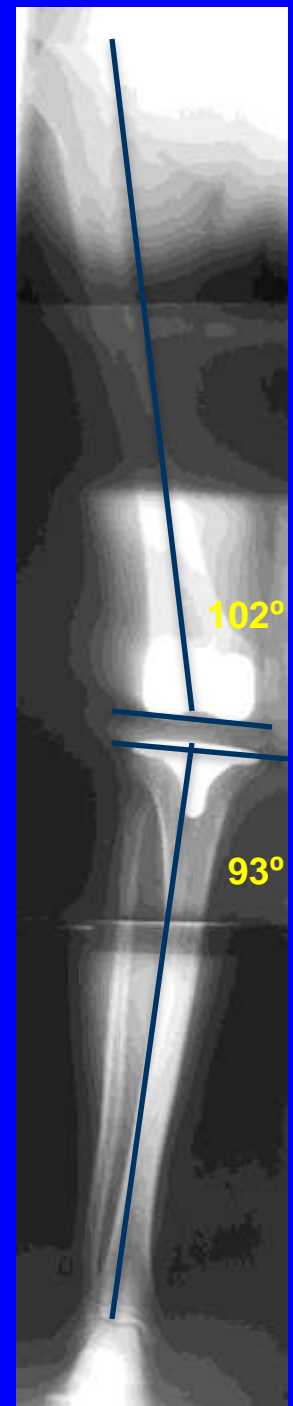
# Recurrent Dislocation Patella

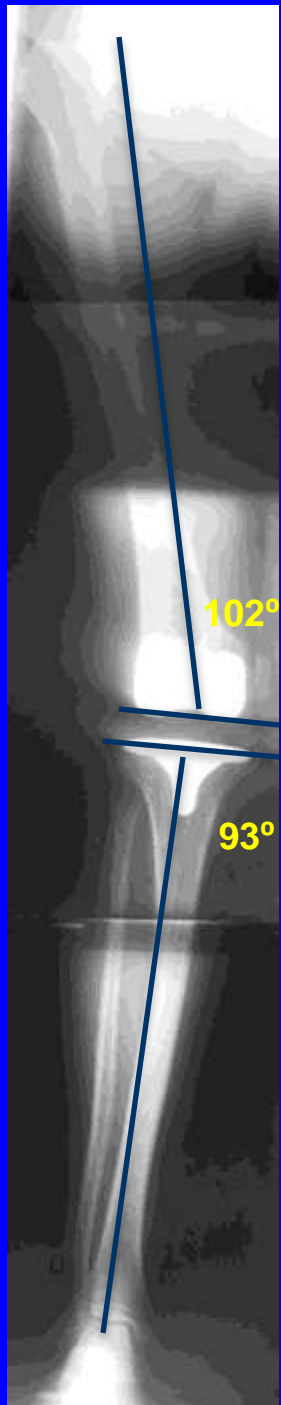
## Where is the Deformity?

$$\text{Femur} = 93^{\circ} - 102^{\circ} = 9^{\circ}$$

$$\text{Joint} = 0^{\circ}$$

$$\text{Tibia} = 93^{\circ} - 87^{\circ} = 6^{\circ}$$





# Deformity

$$\text{Femur} = 93^{\circ} - 102^{\circ} = 9^{\circ}$$

$$\text{Joint} = 0^{\circ}$$

$$\text{Tibia} = 93^{\circ} - 87^{\circ} = 6^{\circ}$$

$$\text{Femur } 9^{\circ} + \text{Joint } 0^{\circ} + \text{Tibia } 6^{\circ}$$

Correct by

Osteotomy Femur  $9^{\circ}$

+

Osteotomy Tibia  $6^{\circ}$

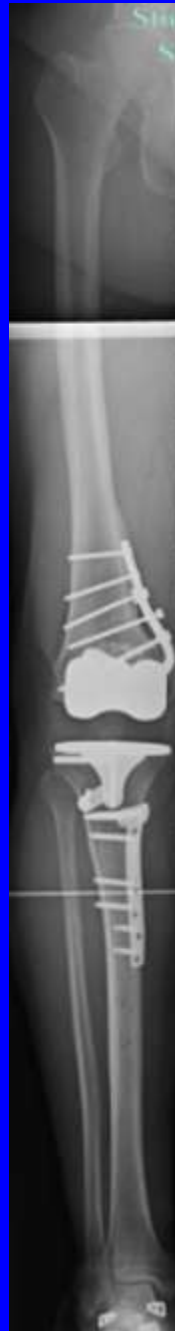
+

MPFL Reconstruction

Very Happy with result



# 11 mo Post Op



# Double Osteotomy for Patellar Dislocation



# Summary

## Deformity Calculation

1. Draw the Mechanical Axis
2. Calculate the Total Deformity (Angle from Hip-Knee-Ankle)
3. Draw the Joint Deformity (Angle Bottom Femur & Top Plateau)
4. Draw the Femoral Deformity
5. Draw the Tibial Deformity
6. Add: Femoral Deformity + Joint Deformity + Tibial Deformity = Hip-Knee-Ankle Angle (= Total Deformity)



# **Osteotomy**

## **There are many ways to Plan**

**Objective is to have the Mechanical Axis pass through the knee joint so the body weight loads the healthy compartment and unloads the arthritic compartment**

**One Plan: Move the Mechanical Axis to where you would like it to be  
Surgeon's Choice**

# Planning Osteotomy

1. **Decide which bone you want to correct - Femur or Tibia?**  
You must know where the deformity is!
2. *Draw a new mechanical axis* where you want it to pass through the knee joint – surgeon's choice - For correction on the femur draw from the talus through knee. For a correction on the Tibia draw from the femoral head center through the knee joint
3. **Decide where you want to put the osteotomy – surgeon's choice** Normally put osteotomy where the deformity is. Mark the apex of the correction.
4. **Femoral Osteotomy:** Draw from the femoral head to the apex of correction angle. Draw a second line from the apex of correction to the new mechanical axis the same distance away.
5. **Tibial Osteotomy:** draw from the Talus to the apex of correction to the new mechanical axis.

## One Method:

1. Draw the New (Desired) Mechanical Axis
2. Select the location for osteotomy,
3. Select the location for the apex of the cut.
4. Draw Lines from the Talus Center to the apex of the correction angle then from the apex to the new mechanical axis

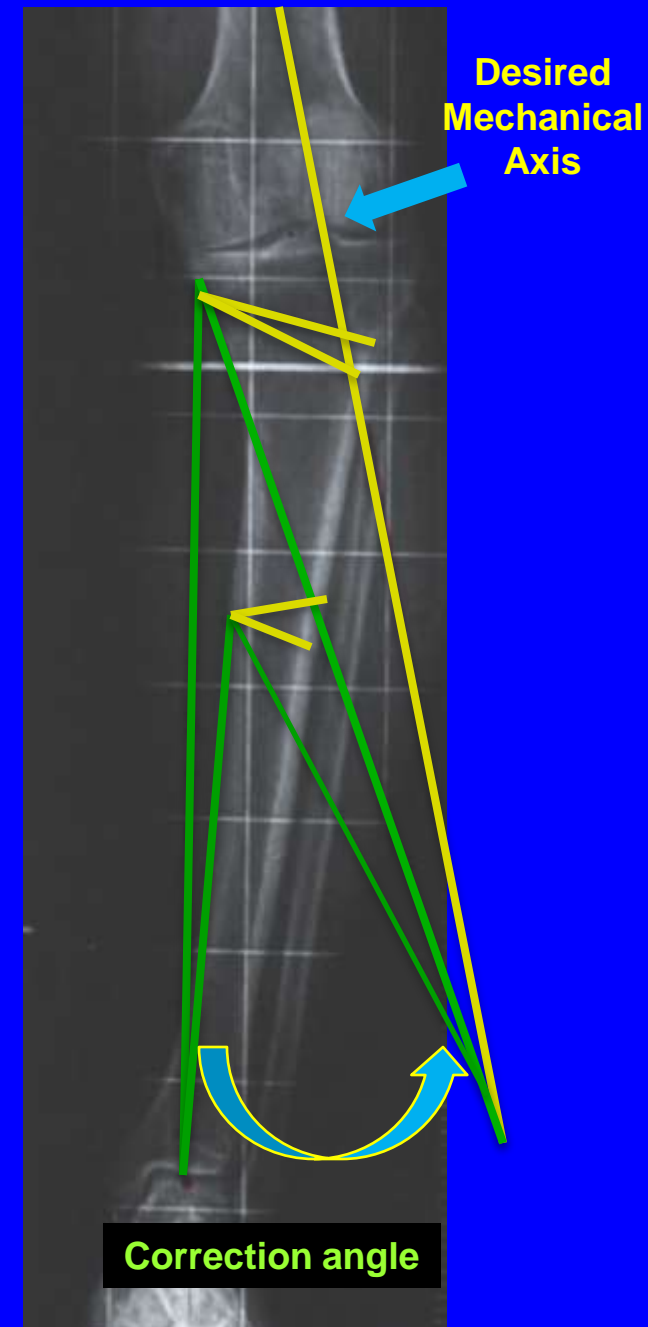
**This is the correction angle**



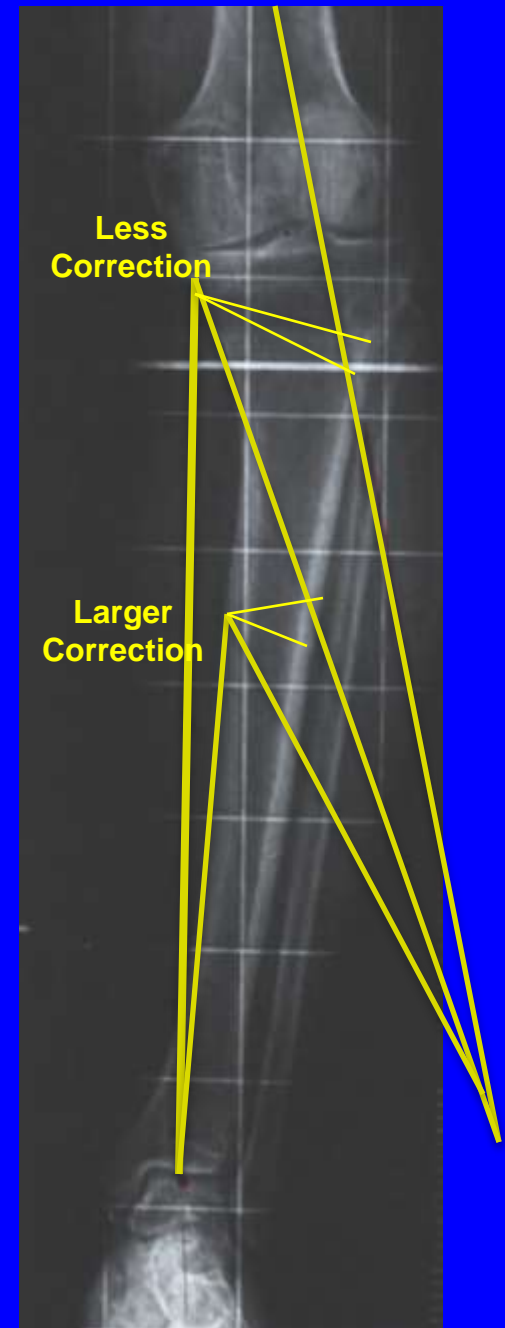
## To Determine the Angle needed for correction Closing Wedge:

1. Select the *location for the osteotomy*.  
Select the point about which fragments will be rotated (the apex of the angle of correction).
2. Draw the *desired mechanical axis*.  
Where do you want the new mechanical axis to cross the knee joint?
3. Draw lines from the center of the talus to the pivot point (apex of correction angle) and from the apex to the intersection with the new mechanical axis.

This is Correction angle



**The Farther The  
Osteotomy is from  
the Deformity  
The Larger the  
Correction Needed**



**For Correction at the  
*Femur* – Draw the New  
(Desired) Mechanical  
Axis from the Talus  
through the knee joint  
proximally**

**The Correction Angle  
is From the Femoral  
Head to Osteotomy  
Apex to New  
Mechanical Axis**



**For Closing Wedge  
Moving into Valgus  
Apex is on Medial  
Side**

**For Opening Wedge  
Moving into Valgus  
Apex is on the  
Lateral Side**

# Summary Osteotomy Planning

**Objective:** Restore Normal Alignment  
+ 2-4° Overcorrection

You Can Not Correct the Joint Deformity with Osteotomy, To compensate for a Joint Deformity add extra deformity to the osteotomy

Pick the bone (Femur or Tibia) with the Most Deformity

Double Osteotomy often good choice when deformity in both Tibia and Femur

# Conclusion

- Osteotomy attempts to provide a mechanical solution to a biological failure
- Goal is to put the Mechanical Axis through the center of the knee slightly more to the healthy side

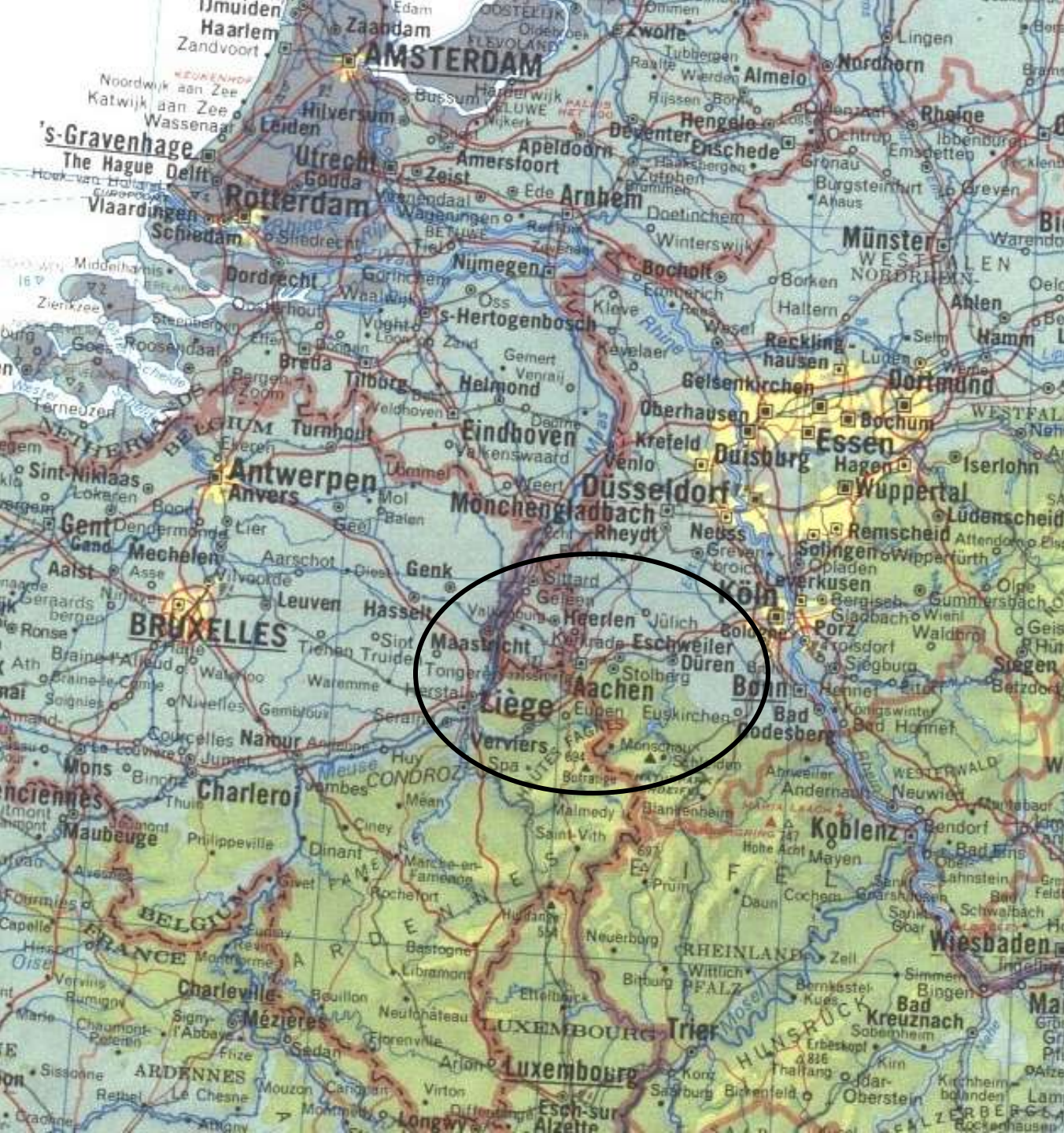


Stop









- Pauwels worked in Aachen

- Maquet worked in Liege

20 Km apart

- Paul Maquet as a young surgeon routinely reviewed his cases with Pauwels.
- Maquet's Book is a masterpiece of understanding limb alignment.

Paul G. J. Maquet

# Biomechanics of the Knee

With Application to the Pathogenesis and the Surgical Treatment of Osteoarthritis

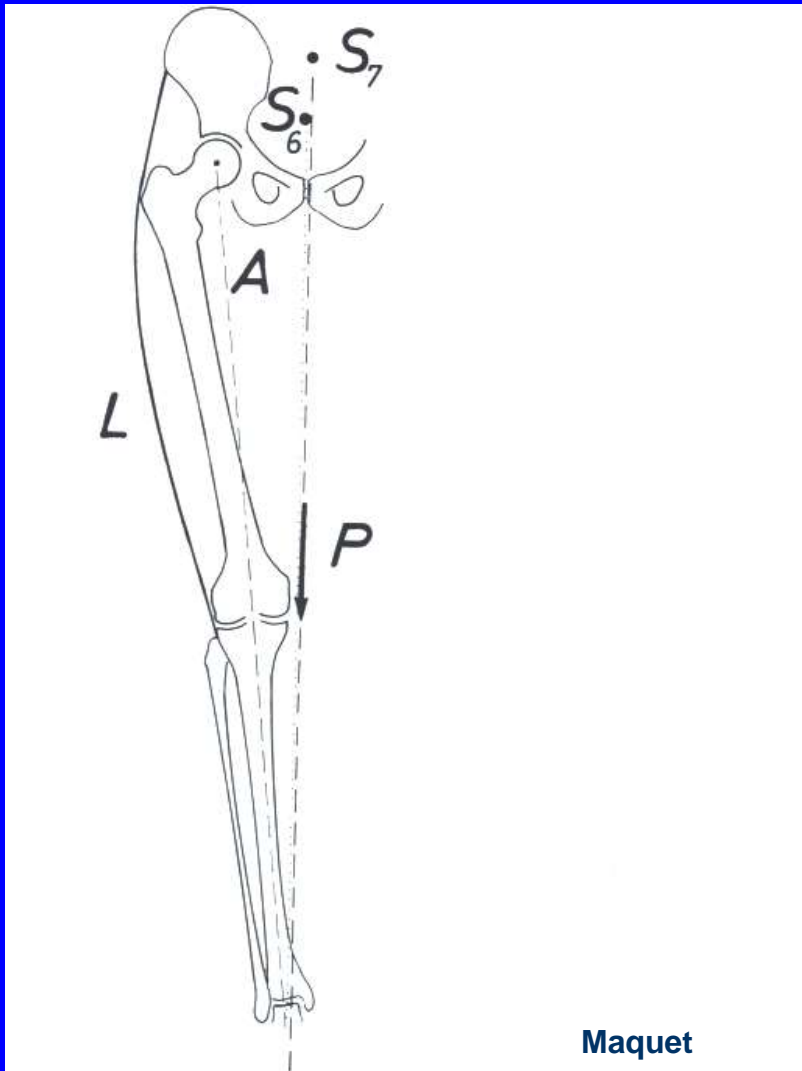
With 184 Figures.



Springer-Verlag Berlin Heidelberg New York



# Forces Crossing the Knee



**P** is the Weight Bearing line (the “P” Vector)

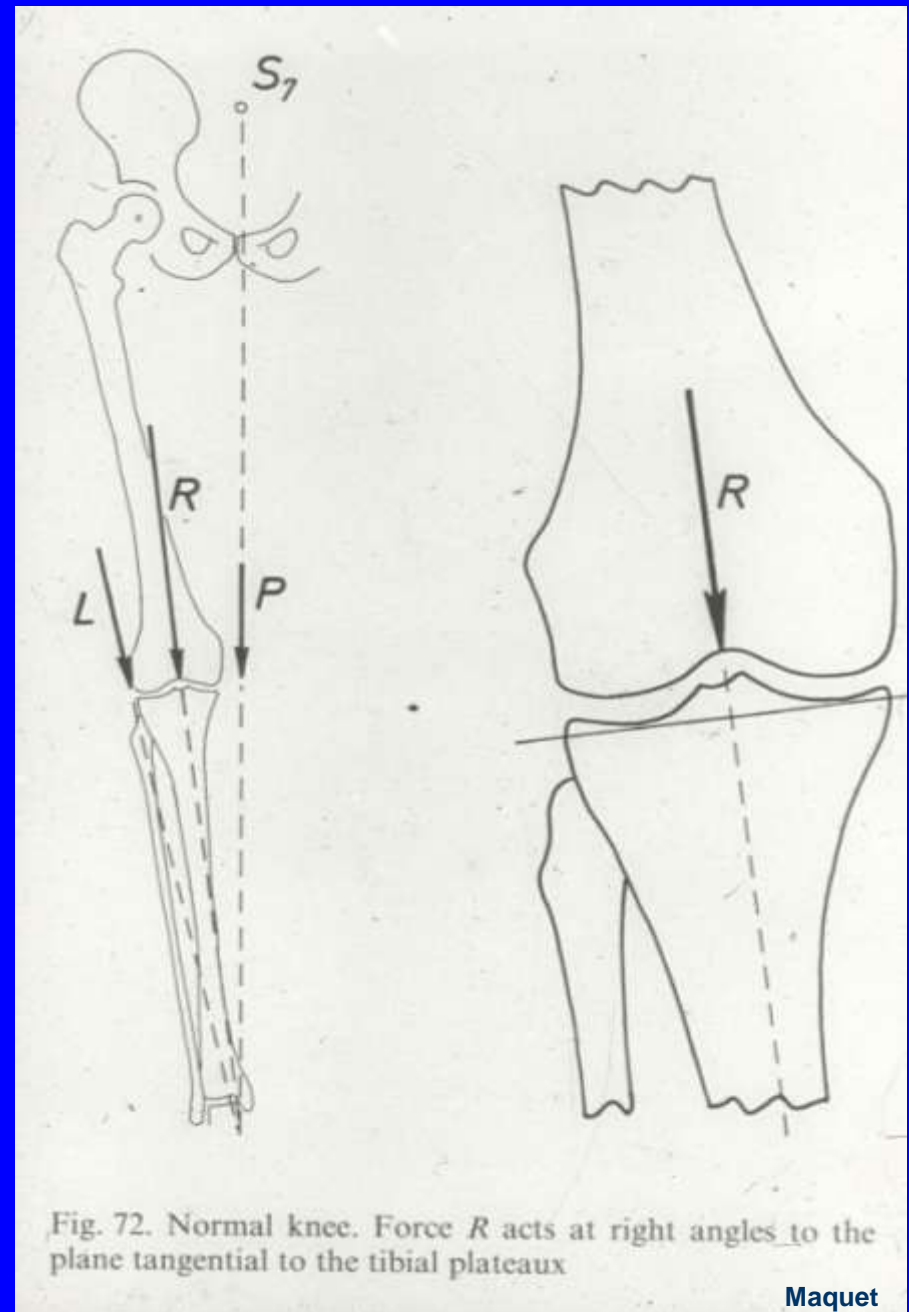
**L** is the lateral muscle vector

**A** is the Mechanical Axis

$S_7$  is the Center of Gravity of the Body

$S_6$  Center of Mass standing on one foot

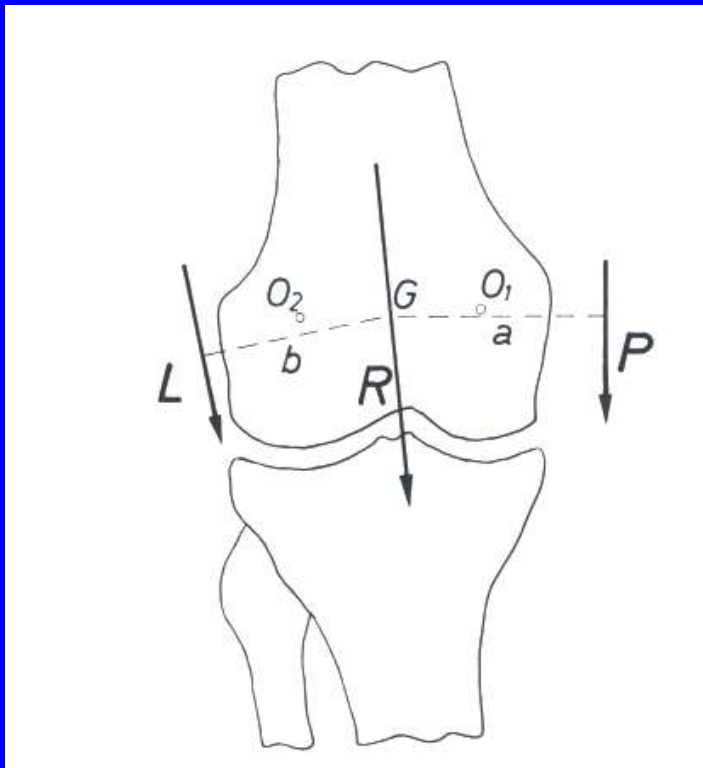
**$R = P + L$**   
( $R$  = resultant  
vector acting  
across the knee  
joint)



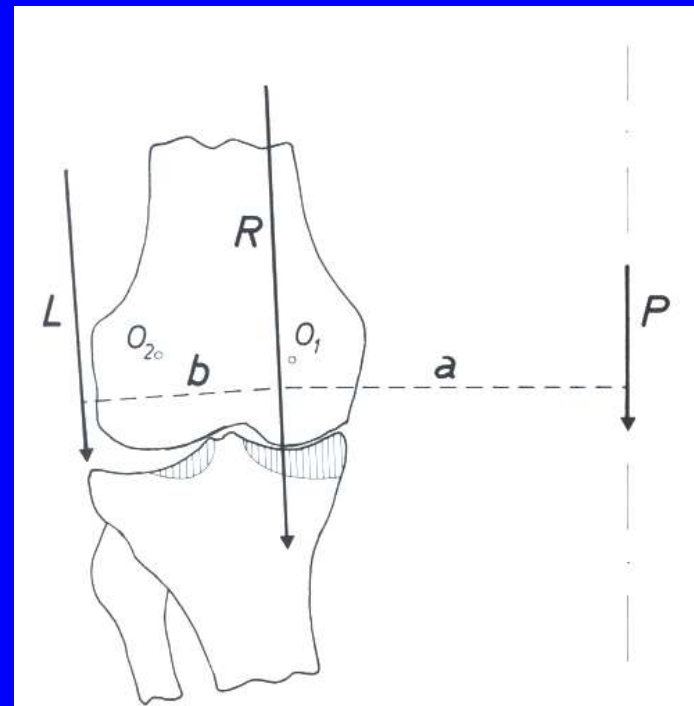


# P (body weight) and L (lateral muscle pull) combine to yield resultant R

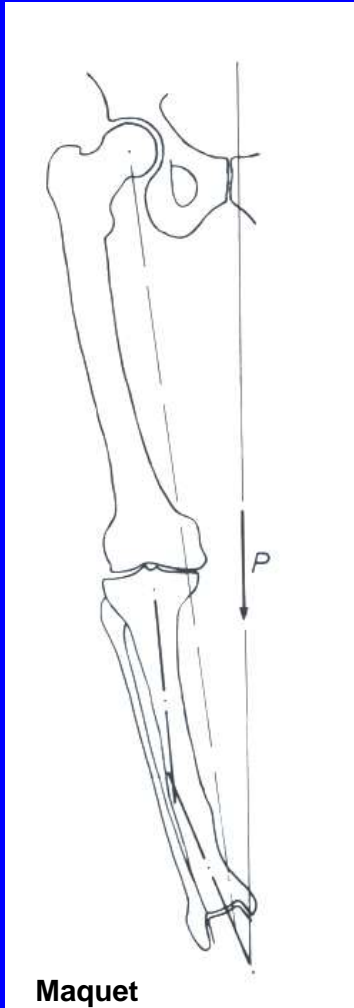
Normal R @ medial spine



Too Much Weight 'P'  
Or  
Too Little Muscle 'L'



# “R” Shifts Medially

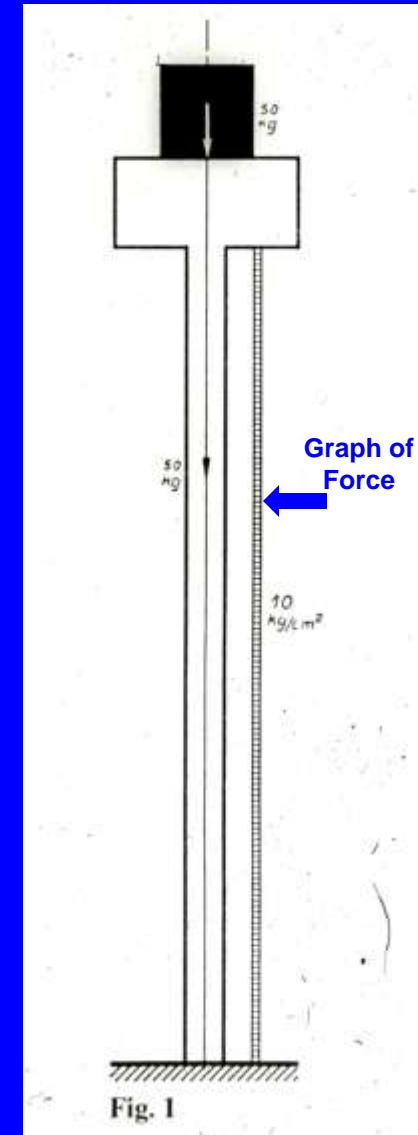


- Varus Malunion
- Congenital Varus
  - Femur
  - Tibia
- Lat Ligament Laxity
- ACL Laxity
- Medial Cartilage Loss

# Pauwels' Challenge: Begin with a Column *and* Design a Lower Limb

Calculations based on  
50 kg centered on a  
 $5\text{cm}^2$

In this drawing  
force =  $10\text{ kg/cm}^2$



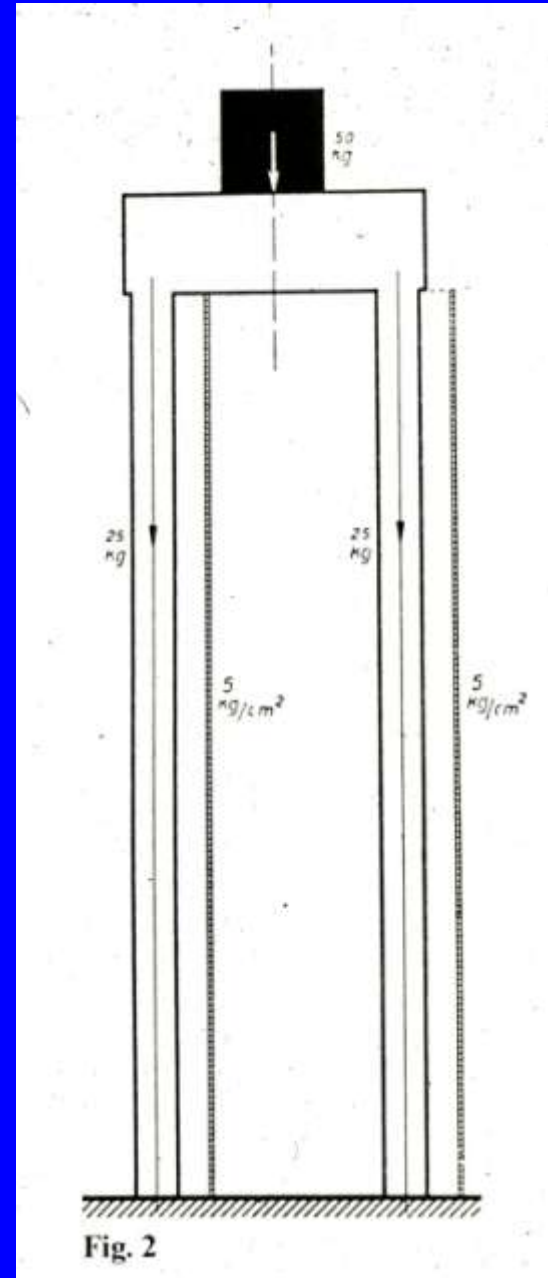
Two Limbs

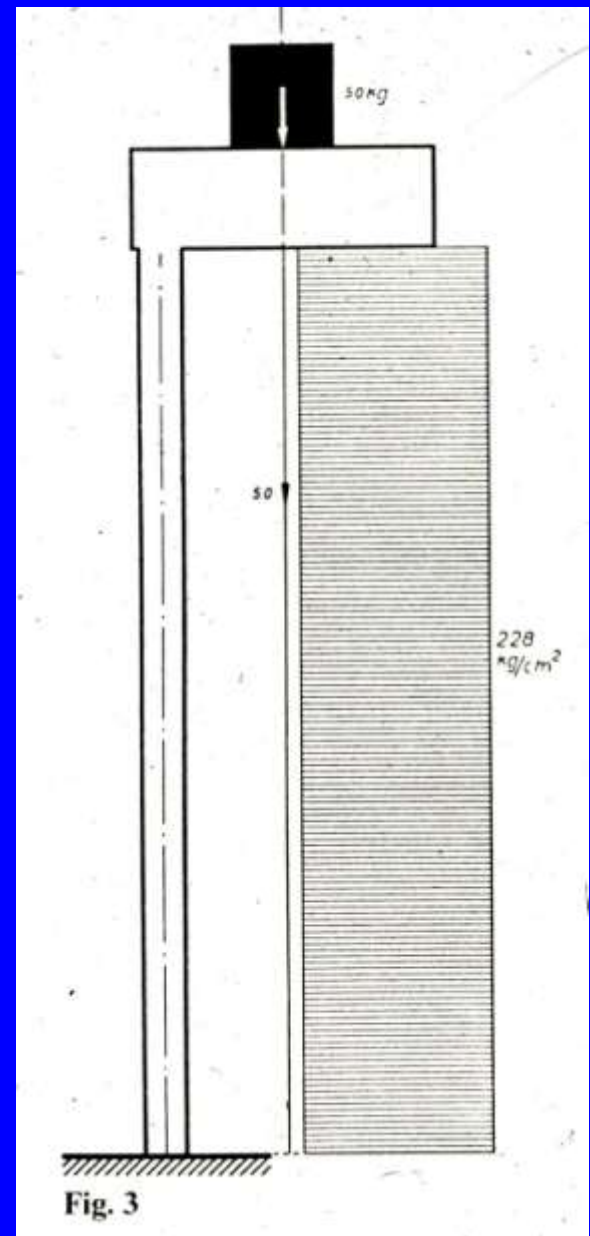
=

Half the

Load

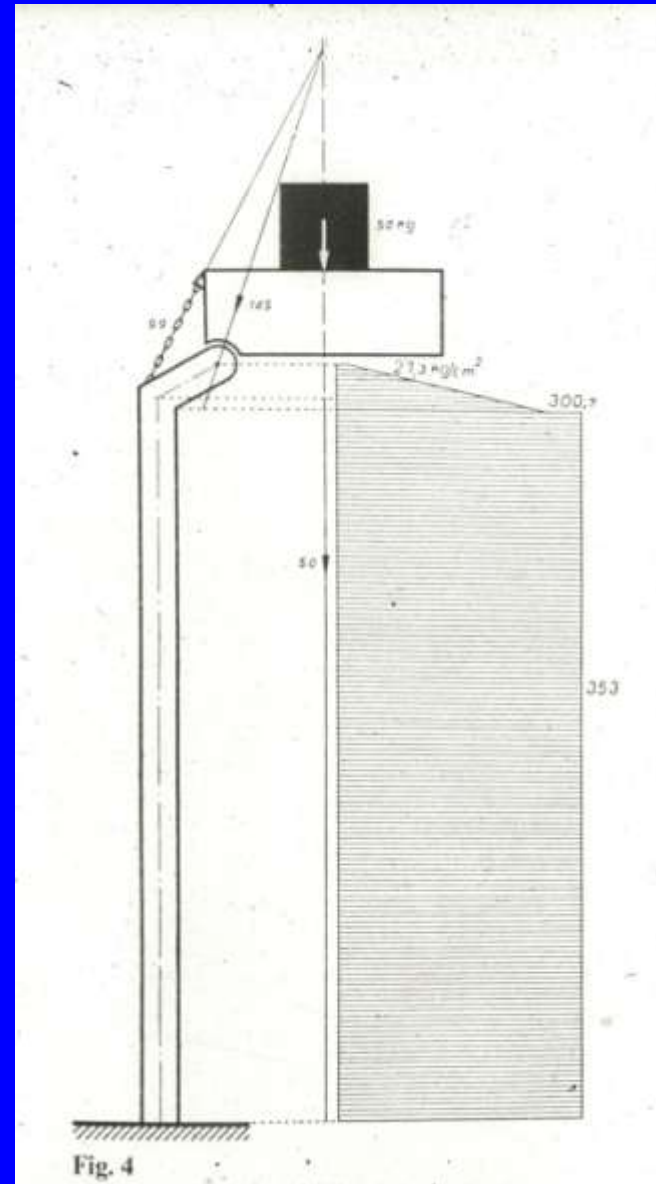
5kg/cm<sup>2</sup>





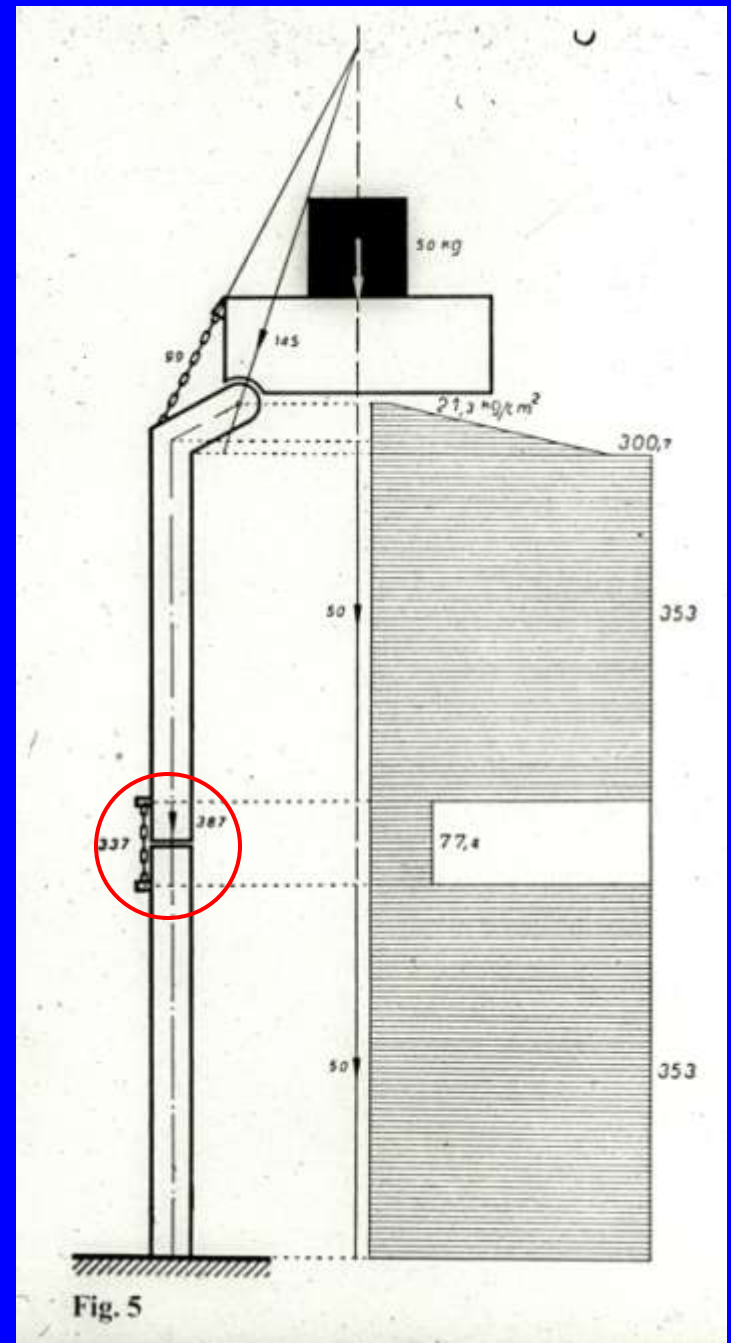
**Adding a Hip  
increases the  
load in the  
column 35 times**

**$353\text{kg/cm}^2$**



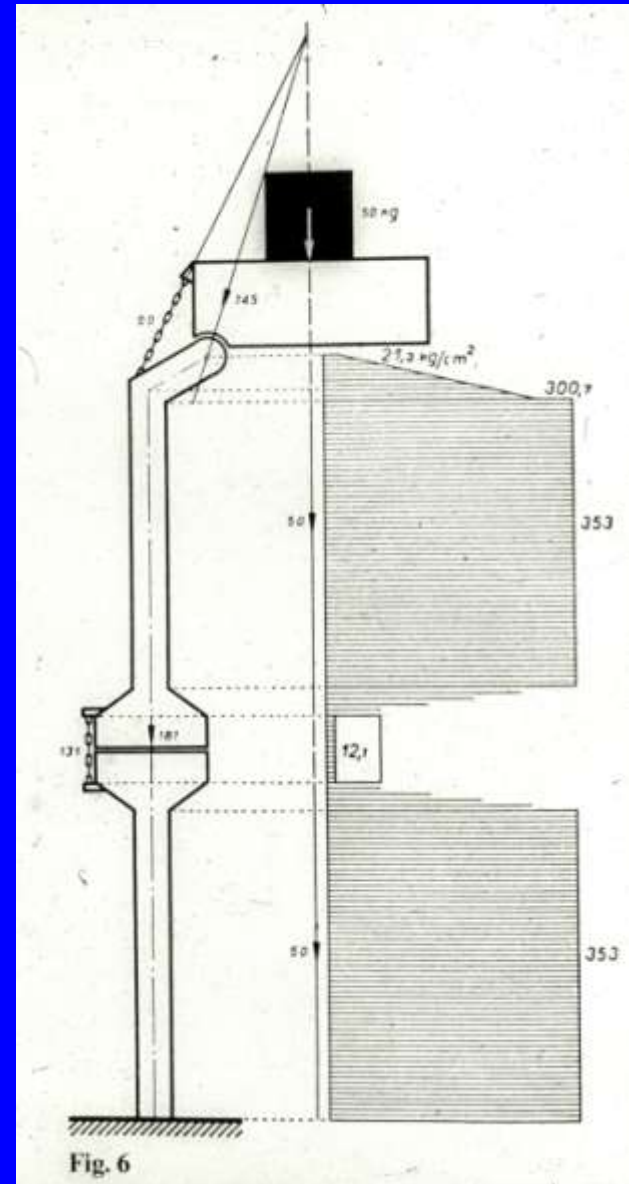
**Adding a Knee  
Joint decreases  
the load in the  
column 5 times  
but shifts it to the  
Ligaments**

**$77\text{kg/cm}^2$**



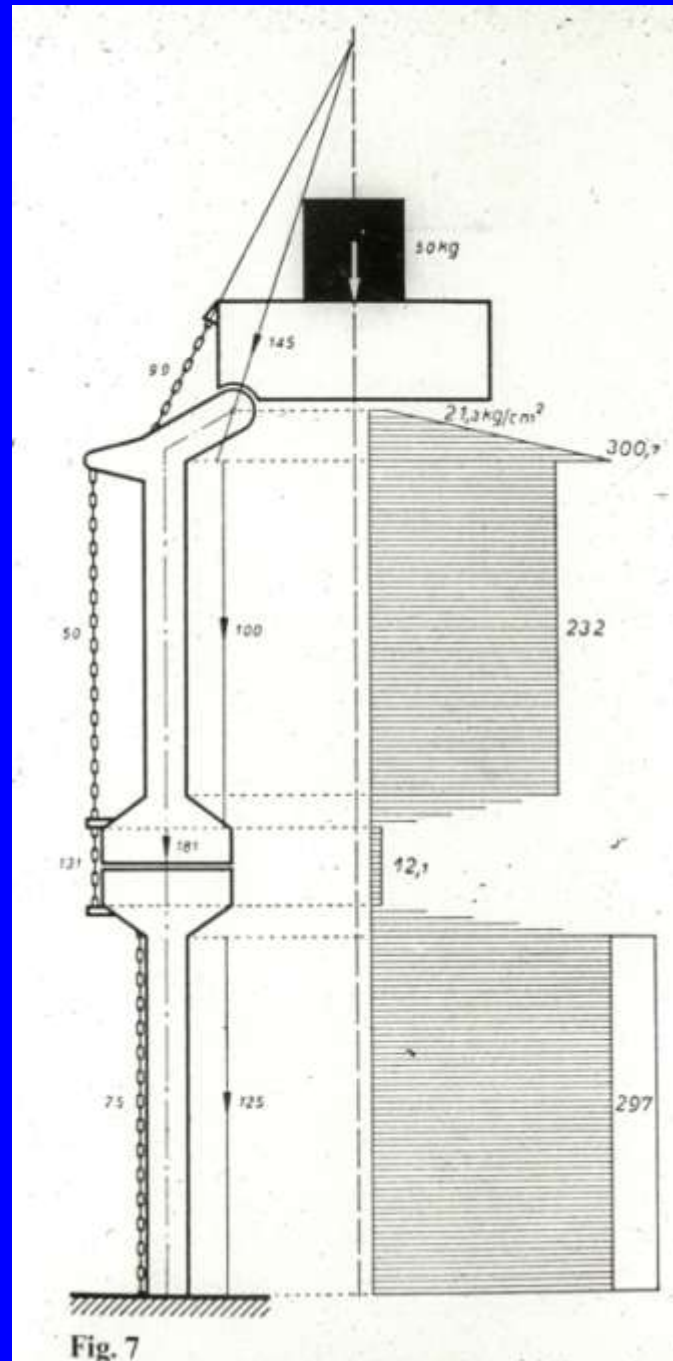
**Increasing Knee  
Surface Area  
decreases Unit  
Pressure and  
Ligament Tension**

**$12\text{kg/cm}^2$**





**Adding Lateral  
Tension Bands  
and Trochanter  
decreases the  
unit load in the  
column**



**Inclining the limb  
markedly  
decreases both  
unit loads and  
ligament  
tensions**

**(Need a subtalar joint)**

